

1. Diagonalize the following matrices (over the real numbers) if possible. If the matrix is diagonalizable, calculate A^{100} .

a. $A = \begin{bmatrix} 0 & 2 \\ -2 & 0 \end{bmatrix}$

First, we find the eigenvalues: we see that $p_A(\lambda) = \det(A - \lambda I) = \det \begin{bmatrix} -\lambda & 2 \\ -2 & -\lambda \end{bmatrix} = \lambda^2 + 4$.

The roots of the characteristic polynomial are complex, so this matrix is not diagonalizable over the real numbers.

You were not required to calculate A^{100} , but as an aside:

$A = 2 \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$ so $A^{100} = 2^{100} \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}^{100}$. Let $B = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$. Examine a few powers:

$$B^2 = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} \quad B^4 = B^2 B^2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I$$

$$\text{So, } A^{100} = 2^{100} B^{100} = 2^{100} (B^4)^{25} = 2^{100} I^{25} = 2^{100} I = \begin{bmatrix} 2^{100} & 0 \\ 0 & 2^{100} \end{bmatrix}.$$

b. $A = \begin{bmatrix} -3 & -2 \\ 4 & 3 \end{bmatrix}$

To diagonalize, we need the eigenvalues and eigenvectors.

An eigenvector is a vector \mathbf{v} that satisfies the equation $A\mathbf{v} = \lambda\mathbf{v}$ where $\mathbf{v} \neq \mathbf{0}$ for some scalar λ , the eigenvalue. To find these we examine the related system $(A - \lambda I)\mathbf{v} = \mathbf{0}$. As we need non-zero vectors that satisfy this equation, we know the matrix $(A - \lambda I)$ must not be invertible (this was one of our characterizations for a singular matrix!).

We can find out which values of λ cause this to happen (the eigenvalues of A) by finding the roots of the characteristic polynomial $p_A(\lambda) = \det(A - \lambda I)$. (i.e., we are looking for values of λ that make the matrix $(A - \lambda I)$ singular).

Once we know the eigenvalues, we can find the eigenvectors by solving the equation $(A - \lambda I)\mathbf{v} = \mathbf{0}$ for each of the eigenvalues.

First, we find the characteristic polynomial:

$$\begin{aligned}
 p_A(\lambda) &= \det(A - \lambda I) = \det \begin{bmatrix} -3 - \lambda & -2 \\ 4 & 3 - \lambda \end{bmatrix} \\
 &= (-3 - \lambda)(3 - \lambda) + 8 = -9 + 3\lambda - 3\lambda + \lambda^2 + 8 = \lambda^2 - 1
 \end{aligned}$$

The roots of the characteristic polynomial are the eigenvalues, $\lambda_1 = 1$ and $\lambda_2 = -1$.

Solving for the eigenvectors:

For $\lambda_1 = 1$:

$$(A - \lambda_1 I)\mathbf{v} = \mathbf{0} = \begin{bmatrix} -4 & -2 \\ 4 & 2 \end{bmatrix} \mathbf{v} = \mathbf{0}. \text{ By Gaussian elimination,}$$

$$\begin{bmatrix} -4 & -2 \\ 4 & 2 \end{bmatrix} \xrightarrow{R_2 = R_2 + R_1} \begin{bmatrix} -4 & -2 \\ 0 & 0 \end{bmatrix} \text{ so in equation form our only constraint is}$$

$-4x_1 - 2x_2 = 0$ or $x_2 = -2x_1$. We'll take x_1 as the free variable. If α is any real number

our solution set is $\begin{bmatrix} \alpha \\ -2\alpha \end{bmatrix} = \alpha \begin{bmatrix} 1 \\ -2 \end{bmatrix}$, so the eigenvector corresponding with $\lambda_1 = 1$ is

$$\mathbf{v}_1 = \begin{bmatrix} 1 \\ -2 \end{bmatrix}.$$

For $\lambda_2 = -1$:

$$(A - \lambda_2 I)\mathbf{v} = \mathbf{0} = \begin{bmatrix} -2 & -2 \\ 4 & 4 \end{bmatrix} \mathbf{v} = \mathbf{0}. \text{ By Gaussian elimination,}$$

$$\begin{bmatrix} -2 & -2 \\ 4 & 4 \end{bmatrix} \xrightarrow{R_2 = R_2 + 2R_1} \begin{bmatrix} -2 & -2 \\ 0 & 0 \end{bmatrix} \text{ so in equation form our only constraint is}$$

$-2x_1 - 2x_2 = 0$ or $x_2 = -x_1$. We'll take x_1 as the free variable. If α is any real number

our solution set is $\begin{bmatrix} \alpha \\ -\alpha \end{bmatrix} = \alpha \begin{bmatrix} 1 \\ -1 \end{bmatrix}$, so the eigenvector corresponding with $\lambda_2 = -1$ is

$$\mathbf{v}_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}.$$

To diagonalize:

$$X = [\mathbf{v}_1 \quad \mathbf{v}_2] = \begin{bmatrix} 1 & 1 \\ -2 & -1 \end{bmatrix}, \quad X^{-1} = \frac{\text{adj } X}{\det X} = \frac{1}{1} \begin{bmatrix} -1 & 2 \\ -1 & 1 \end{bmatrix}^T = \begin{bmatrix} -1 & -1 \\ 2 & 1 \end{bmatrix}. \text{ By our construction}$$

$$\text{we know that } D = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}.$$

Alternately, we could solve for D :

$$D = X^{-1}AX = \begin{bmatrix} -1 & -1 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} -3 & -2 \\ 4 & 3 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ -2 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}.$$

$$\text{So } A = XDX^{-1} = \begin{bmatrix} 1 & 1 \\ -2 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} -1 & -1 \\ 2 & 1 \end{bmatrix}.$$

Calculations of the form A^{100} were discussed a few times. For a reminder, see the comment in your book following theorem 6.3.2, your discussion notes, or homework section 6.3 #2. To summarize:

Powers of A are easy when represented in this diagonalized form. To see why, examine $A^2 = (XDX^{-1})(XDX^{-1}) = XD(X^{-1}X)DX^{-1} = XD^2X^{-1}$. The same grouping works for any positive integer power, so $A^n = XD^nX^{-1}$. Diagonal matrices are easy to multiply; multiplying out a few terms should convince you that $D^n = \begin{bmatrix} \lambda_1^n & 0 \\ 0 & \lambda_2^n \end{bmatrix}$.

$$A^{100} = XD^{100}X^{-1} = X \begin{bmatrix} 1^{100} & 0 \\ 0 & -1^{100} \end{bmatrix} X^{-1} = XIX^{-1} = XX^{-1} = I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}.$$

2. Find the 3rd Taylor Polynomial $p_3(x)$ expanded about $c = 1$ for the following:

$$f(x) = \sin(x)$$

$$p_3(x) = f(c) + \frac{f^{(1)}(c)}{1!}(x-c)^1 + \frac{f^{(2)}(c)}{2!}(x-c)^2 + \frac{f^{(3)}(c)}{3!}(x-c)^3$$

$$f^{(1)}(x) = \cos(x), \quad f^{(2)}(x) = -\sin(x), \quad f^{(3)}(x) = -\cos(x) \quad \text{so}$$

$$p_3(x) = \sin(1) + \cos(1)(x-1) - \frac{\sin(1)}{2}(x-1)^2 - \frac{\cos(1)}{6}(x-1)^3.$$